

# Communication

## Wideband 3D-Printed Transmit-Reflect-Array Antenna with Independent Beam Control

Zhenqin Zheng, Long Zhang, *Member, IEEE*, Qi Luo, *Senior Member, IEEE*, Chunxu Mao, *Member, IEEE*, Yejun He, *Senior Member, IEEE*, and Steven Gao, *Fellow, IEEE*

**Abstract**—This paper proposes a wideband 3D-printed transmit-reflect-array (TRA) antenna. The transmission and reflection functions of this TRA antenna are determined by the polarization of the incident electromagnetic wave. The proposed TRA element is composed of a dielectric post and three copper wires, which can be realized by the low-cost 3D printing. Attributed to the independent control of transmission and reflection phase shift of the proposed element within a wide bandwidth, the proposed TRA antenna can generate two independent transmission and reflection beams over a wide bandwidth. A  $12 \times 12$  TRA is designed, fabricated, and measured to verify the design concept. The measured results show that a peak gain of 24.4 dBi with a bandwidth of 46.8% (18–29 GHz) for the transmitarray function and a peak gain of 22.9 dBi with a bandwidth of 52.2% (17–29 GHz) for the reflectarray function are achieved simultaneously by the 3D-printed TRA antenna. The wide bandwidth, high gain, independent beam control capability, combined transmit/reflectarray functions and low fabrication cost make the proposed antenna appealing for various wireless applications.

**Index Terms**—3D-printed antenna, transmit-reflect-array antenna, wideband antenna.

### I. INTRODUCTION

WITH the development of wireless communications, transmitarrays (TAs) and reflectarrays (RAs) attracted ever-growing attentions [1], [2]. TAs/RAs combine the advantages of lens/reflector antennas and phased array antennas, thus have merits of high gain, low cost, and light weight.

Previous researches mainly focus on improving the performances of TA and RA, such as improving the bandwidth [3]–[8], the beam versatility [9]–[11], and reconfigurability [12]–[15]. However, most of the reported TAs and RAs can only generate a pencil beam towards one direction, which limits their potential applications. Nevertheless, bidirectional antennas are demanded by various wireless systems, such as tunnel relay communications, broadcasting base stations, and

interferometric synthetic aperture radars. If multiple antennas are used to fulfill the required bidirectional function, the whole system will be bulky and of high fabrication cost and design complexity. Therefore, considerable efforts have been devoted to combining the TA and RA into one design [16]–[23]. In [16], a high-gain bidirectional transmit-reflect-array (TRA) antenna that has a near-zero thickness was proposed. The measured gain of TA and RA are 25.5 dBi and 25 dBi, respectively. However, the transmitted and reflected beams of this design cannot be controlled independently, i.e., the transmitted and reflected beams are symmetric with respect to the planar aperture. In [17], a TRA consisting of four metallic layers and three F4B substrates was proposed. Although it can control the beams of TA and RA independently, the 1-dB gain bandwidth is only 9.14%. For the TRA proposed in [18], the TRA is obtained by using the sparse-array method, of which parts of the elements are transmission elements and the others are reflection elements. Although it can control the beams of TA and RA independently, the 1-dB gain bandwidths of transmission and reflection are only 6.7% and 9.3%, respectively.

Recently, the emerging 3D-printing technology is used to fabricate TAs and RAs to reduce the fabrication cost and provide more design flexibility [24]–[26]. In [24], a 3D-printed dielectric RA was proposed with low cost and high gain at sub-millimeter-wave bands. The  $360^\circ$  phase shift is achieved by changing the height of the 3D-printed dielectric slab. For the 3D-printed terahertz TA proposed in [25], the antenna gain ranges from 19.4 to 23.5 dBi within the operating band (50–67.5 GHz). Although these 3D-printed antennas achieve good RA or TA performances, the transmission and reflection functions have not been achieved simultaneously by a single 3D-printed antenna.

To solve these issues, a wideband 3D-printed TRA antenna with transmission and reflection functions depending on the polarization of incident electromagnetic wave is proposed in this paper. The developed TRA element consists of a dielectric post and three copper wires. The phase shift ranges of the proposed element are  $450^\circ$  and  $920^\circ$  for transmission and reflection, respectively, which can be controlled independently by changing the dielectric post height and positions of the copper wires. For the  $x$ -polarization incident wave, the transmission function is realized and the reflection function is achieved for  $y$ -polarization waves. Therefore, the proposed TRA can generate two independent forward and backward pencil beams simultaneously by using a dual-linearly-polarized horn as the feed antenna. To prove the design concept, a  $12 \times 12$  3-bit

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Z. Zheng, L. Zhang and Y. He are with the College of Electronics and Information Engineering, Shenzhen University, Shenzhen 518060, China (e-mail: zhenqin20@163.com, long.zhang@szu.edu.cn, heyeyun@126.com).

Q. Luo is with the School of Physics, Engineering and Computer Science, University of Hertfordshire, Hertfordshire AL109AB, U.K. (e-mail: qiluo@ieee.org).

C. Mao is with the Institute for Communication Systems (ICS), 5G Innovation Centre (5GIC), University of Surrey, Guildford, GU2 7XH, U.K. (c.mao@surrey.ac.uk).

S. Gao is with the Department of Electronic Engineering, Chinese University of Hong Kong (e-mail: scgao@ee.cuhk.edu.hk).

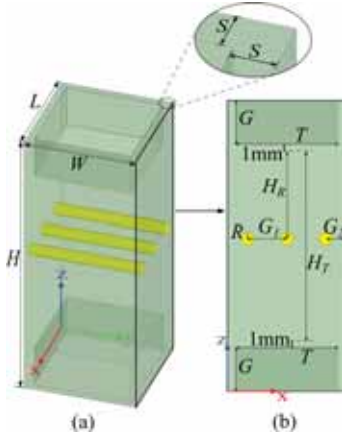


Fig. 1. The configuration of the proposed TRA element: (a) 3D view, (b) side view. ( $W=L=7.5$  mm,  $R=0.4$  mm,  $G_1=2\times G_2=2.5$  mm,  $G=2.8$  mm,  $T=6.5$  mm,  $S=0.5$  mm).

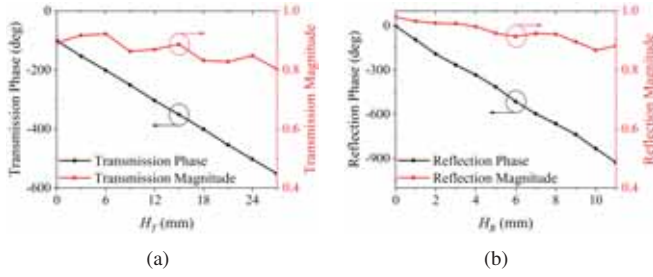


Fig. 2. (a) Transmission magnitude and phase curves versus  $H_T$  at 20 GHz. (b) Reflection magnitude and phase curves versus  $H_R$  at 20 GHz.

TRA is designed, fabricated, and measured. The measured results indicate that the transmission function works within a bandwidth of 46.8% (18–29 GHz) with a maximum gain of 24.4 dBi and the reflection function operates over a bandwidth of 52.2% (17–29 GHz) with a maximum gain of 22.9 dBi. Moreover, the radiation patterns for both functions are stable over the wide operating bandwidth with a low side-lobe level. These merits make the proposed antenna very suitable for wideband wireless applications where bidirectional beams are required.

## II. ANTENNA DESIGN AND OPERATING PRINCIPLE

### A. Design of the TRA Element

The configuration of the proposed TRA element is illustrated in Fig. 1, which is composed of a dielectric post and three copper wires. The dielectric post has a relative permittivity of 2.9 and a loss tangent of 0.0241. Two square holes with a height of  $G$  and a width of  $T$  located in the upper and lower edge of the dielectric post are used to reduce the reflection caused by impedance mismatch [25]. By adding the square holes at the air-dielectric interfaces, the impedance of the dielectric post change. Good impedance matching can be achieved by optimizing the width  $T$  and the height  $G$  of the square holes. Theoretically, the height  $G$  should satisfy [25]

$$G = \frac{\lambda_0}{4 \times (\epsilon_r \times \epsilon_0)^{1/4}} \quad (1)$$

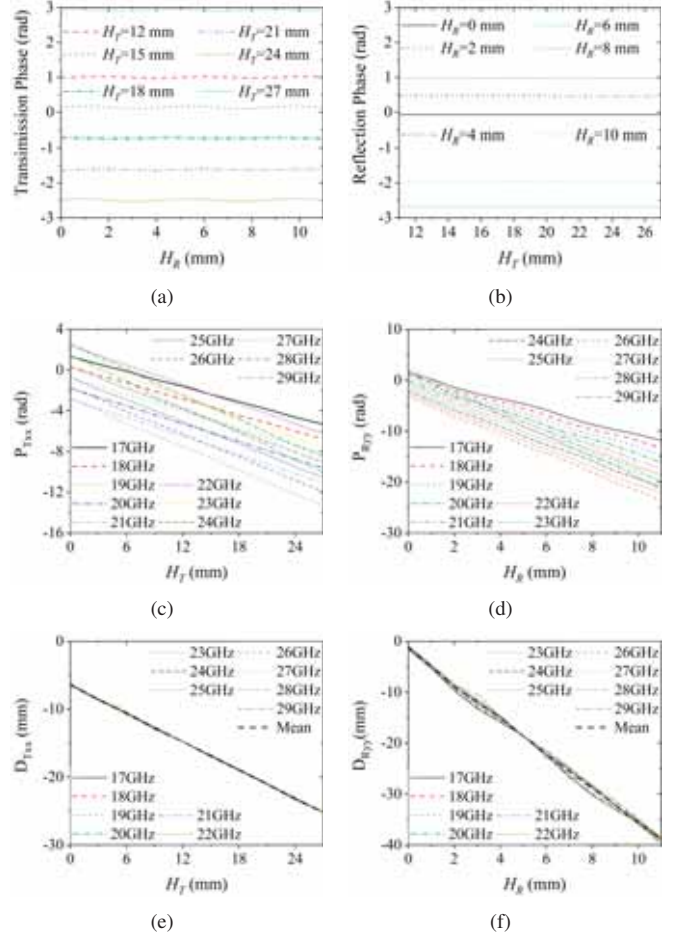


Fig. 3. (a) Transmission phase with different  $H_R$  and  $H_T$  values. (b) Reflection phase with different  $H_T$  and  $H_R$  values. (c)  $P_{Txx}$  with different  $H_T$  values from 17 GHz to 29 GHz. (d)  $P_{Ryy}$  with different  $H_R$  from 17 GHz to 29 GHz. (e)  $D_{Txx}$  with different  $H_T$  from 17 GHz to 29 GHz. (f)  $D_{Ryy}$  with different  $H_R$  from 17 GHz to 29 GHz.

In order to minimize the unwanted reflection over the whole operating bandwidth, the optimized parameters are  $T = 6.5$  mm and  $G = 2.8$  mm.

Three copper wires are placed parallel to the  $y$ -axis with a gap of  $G_1$  that is much smaller than the wavelength at 29 GHz. Therefore, the extinction ratio between two orthogonal polarizations becomes quite large below 29 GHz, leading to a good polarizer for the incident wave over a wide bandwidth [27]. Specifically, the  $x$ -polarized wave can transmit through the copper wires, so its propagation distance is dependent on the height  $H$ . On the contrary, the  $y$ -polarized wave will be reflected by the copper wires, thus the propagation distance of  $y$ -polarized wave is determined by the position of copper wires. Tuning the parameter  $H_T$  can change  $H$ , while tuning the parameter  $H_R$  only affects the relative position of the copper wires. Therefore, the propagation distance of the  $x$ -polarized and  $y$ -polarized wave can be independently controlled by the two parameters  $H_T$  and  $H_R$ , respectively. It is worth pointing out that the value of  $H_T$  must be greater than that of  $H_R$ .

As the propagation distance of the incident wave is determined by the two geometry parameters  $H_R$  and  $H_T$  for

reflection and transmission, respectively. Therefore, the transmission and reflection performance can be controlled by tuning these two parameters. Fig. 2 (a) shows the transmission magnitude and phase shift for the  $x$ -polarized wave. As shown, a linear transmission phase response with  $450^\circ$  range is achieved as  $H_T$  varies, and the transmission magnitude is greater than 0.8. Moreover, Fig. 2 (b) shows that a reflection phase range of  $920^\circ$  is also realized when  $H_R$  changes from 0 mm to 11 mm for the  $y$ -polarized wave at 20 GHz. Meanwhile, the magnitude of reflection is greater than 0.86 under all  $H_R$  values.

The key factor to realize independent control of reflection and transmission function is to change the reflection phase without affecting the transmission phase, and vice versa. As shown in Fig. 3 (a), the transmission phase is nearly unchanged when the  $H_R$  is changed. Likewise, it can be seen from Fig. 3 (b) that changing the  $H_T$  barely affects the reflection phase. In other words, these two parameters of the proposed TRA element can independently control the transmission and reflection phase shift.

The proposed element can realize good reflection and transmission phase characteristics over a wide bandwidth because the phase shift of the element is realized by changing the propagation distance of transmission and reflection waves, which is similar to the true-time delay technique [28]. To eliminate the frequency dependent effect of the element phase shift, the reflection and transmission phase shifts are divided by free-space wave number ( $k_0$ ) [8]

$$D_{T_{xx}/R_{yy}} = \frac{P_{T_{xx}/R_{yy}}}{k_0} \quad (2)$$

where  $D_{T_{xx}/R_{yy}}$  and  $P_{T_{xx}/R_{yy}}$  refer to the equivalent distance delay and the phase shift of transmission and reflection, respectively. Fig. 3 (c) and (d) show the phase curves of transmission and reflection from 17 GHz to 29 GHz, while the equivalent distance delay of transmission and reflection are shown in Fig. 3 (e) and (f). As shown in Fig. 3 (e) and (f), the curves of equivalent distance delay for both reflection and transmission are overlapped from 17 GHz to 29 GHz, indicating that the proposed element can compensate the differential spatial phase delay for the proposed TRA over a wide bandwidth [8]. As aforementioned, the proposed element also acts a wideband polarizer that maintains good reflection and transmission efficiency below 29 GHz. Therefore, a wideband TRA operating from 17 GHz to 29 GHz can be realized by using the proposed element according to the the principles of transmitarray/reflectarray antennas [29].

### B. Design of the TRA Antenna

The configuration of the proposed TRA antenna is shown in Fig. 4. A double-ridged horn antenna (DRHA) is used as the feed antenna which can achieve gain range from 10.14 to 17.16 dBi within a wide bandwidth (10-30 GHz). The DRHA is set with a focal distance of 72 mm ( $F/D = 0.8$ ). In order to generate beams in the desired direction ( $\theta, \varphi$ ), the required phase compensation of each element is calculated by

$$\psi(x_i, y_j) = -k((x_i \cos\varphi + y_j \sin\varphi) \sin\theta - R_{ij}) + \phi_0 \quad (3)$$

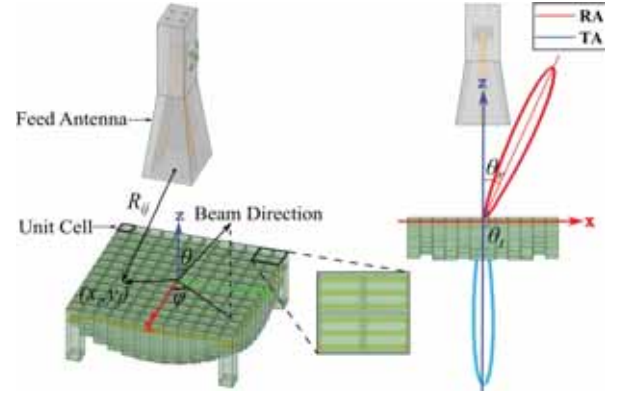


Fig. 4. The configuration of the proposed TRA antenna.

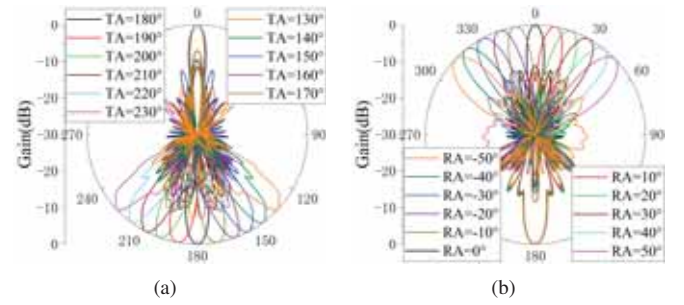


Fig. 5. The simulation radiation patterns of the TRA antenna. (a) Varying transmitted beam directions while fixing the reflected beams to  $0^\circ$ . (b) Varying reflected beam directions while fixing the transmitted beams to  $180^\circ$ .

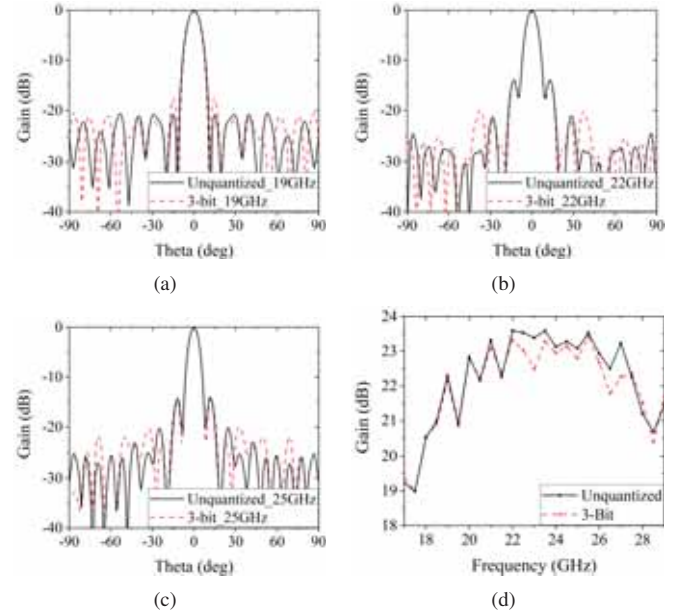


Fig. 6. The comparison of unquantized and 3-bit quantized TRA. (a) Reflection beams at 19 GHz. (b) Reflection beams at 22 GHz. (c) Reflection beams at 25 GHz. (d) Antenna gain.

where  $(x_i, y_j)$  is the position of the element,  $R_{ij}$  is the spatial distance between the feed antenna and the element, and  $\phi_0$  is the initial phase. Using the phase curves of transmission and reflection of the proposed element, the geometry values

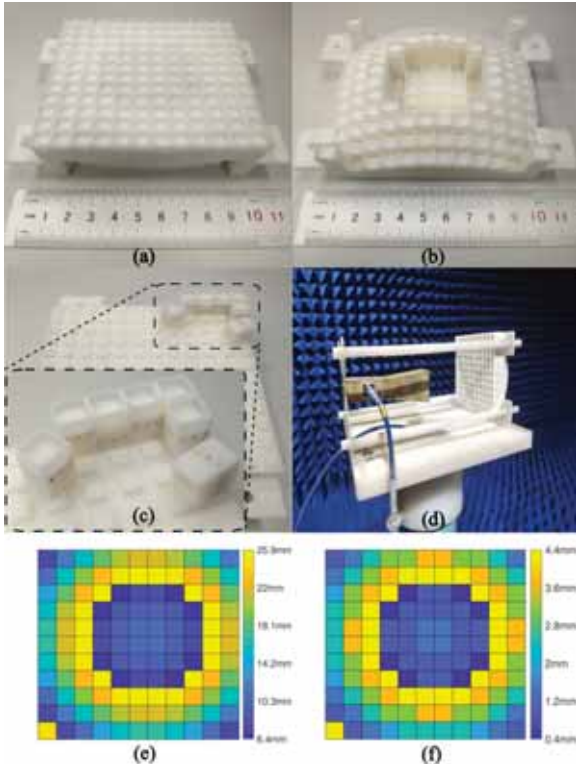


Fig. 7. Fabricated TRA antenna prototype: (a) front view, (b) back view. (c) Demonstration of the mortise and tenon joints. (d) Measurement setup. (e)  $H_T$  value distribution. (f) 3-bit  $H_R$  value distribution.

of each element can be determined according to the phase distributions. Since the value of  $H_T$  is greater than that of  $H_R$ , it is necessary to calculate the  $H_R$  distribution at first. In addition, if the minimum value of  $H_T$  is smaller than the maximum value of  $H_R$ , appropriate  $\phi_0$  should be added to the phase compensation of TA to ensure that  $H_T$  is greater than  $H_R$ .

To verify the independent control of reflection and transmission function, different  $16 \times 16$  TRA antennas using the proposed element with an aperture size of  $120 \text{ mm} \times 120 \text{ mm}$  are designed. The simulation radiation patterns of the TRA antenna with varied transmission and reflection beam directions are shown in Fig.5 (a) and (b), respectively. As shown by these two figures, the transmitted beam directions can be designed from  $130^\circ$  to  $230^\circ$ , while the reflected beam directions can vary from  $-50^\circ$  to  $50^\circ$ . Moreover, the transmission and reflection beams can be controlled independently as these two beams can be designed separately without affecting each other.

### III. RESULTS AND DISCUSSION

In order to reduce the difficulty of fabrication, the phase variation of the RA element is quantized to 3 bits. In other words, the  $H_R$  values are discrete with only eight values that correspond to the reflection phase shift ranging from  $0^\circ$  to  $315^\circ$  with an interval of  $45^\circ$ . To compare the performance of the unquantized and 3-bit TRA antenna, Fig. 6 (a)–(c) presents the normalized radiation patterns of the reflected beams in

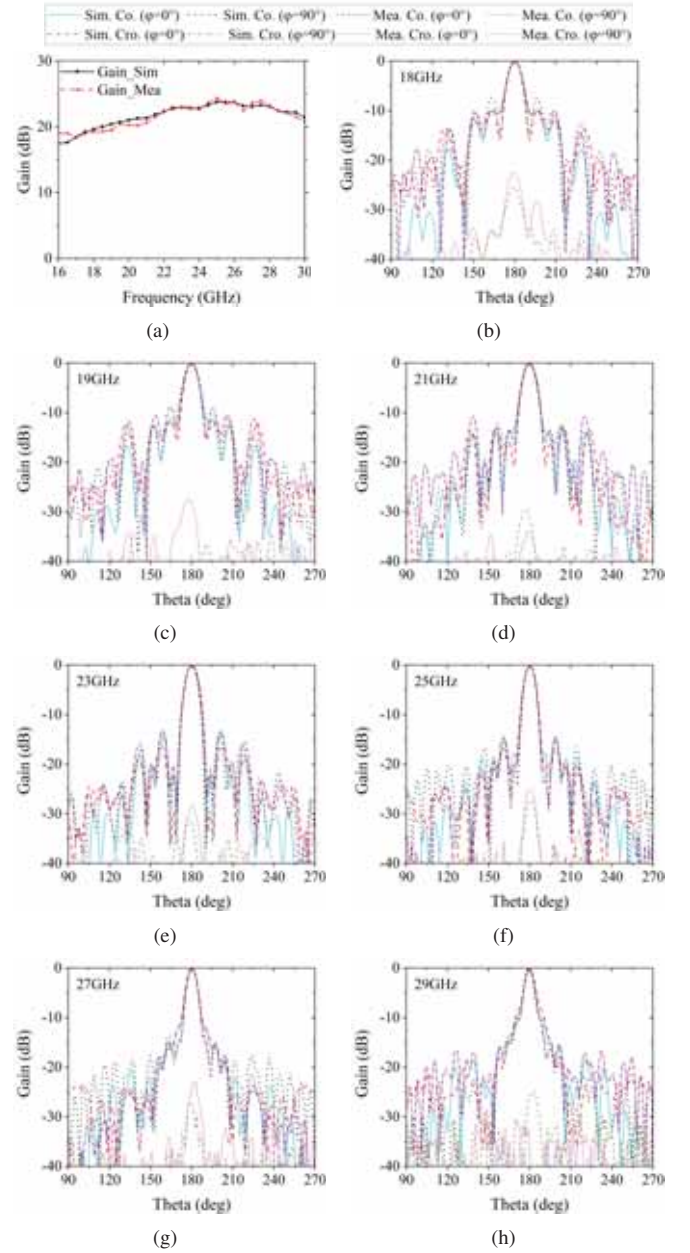


Fig. 8. The gain curves and the radiation patterns of the proposed TRA antenna under transmission function. (a) Gain curves. (b) Radiation patterns at 18 GHz. (c) Radiation patterns at 19 GHz. (d) Radiation patterns at 21 GHz. (e) Radiation patterns at 23 GHz. (f) Radiation patterns at 25 GHz. (g) Radiation patterns at 27 GHz. (h) Radiation patterns at 29 GHz.

$xoz$  plane at 19, 22, and 25 GHz. As can be seen from Fig. 6 (a)–(c), reflected beams of the unquantized and 3-bit TRA antenna are consistent. The sidelobe levels of the 3-bit reflected patterns are slightly greater than that of the unquantized RA. The gain curves of the unquantized and the 3-bit quantized RA are shown in Fig. 6 (d). As shown, the gain difference is small. Therefore, the quantized RA elements will not result in prominent performance degradation to the proposed TRA antenna.

For the convenience of fabrication and measurement, a  $12 \times 12$  TRA antenna with transmission beam direction of  $\theta_t =$

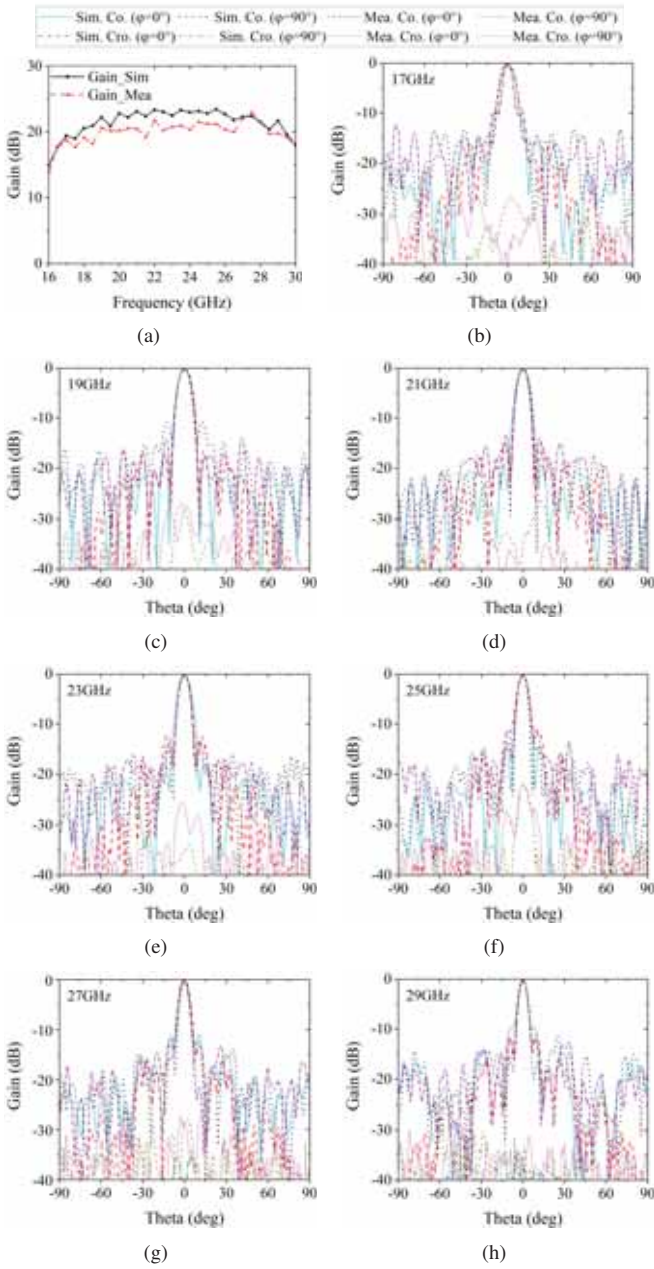


Fig. 9. The gain curves and the radiation patterns of the proposed TRA antenna under reflection function. (a) Gain curves. (b) Radiation patterns at 17 GHz. (c) Radiation patterns at 19 GHz. (d) Radiation patterns at 21 GHz. (e) Radiation patterns at 23 GHz. (f) Radiation patterns at 25 GHz. (g) Radiation patterns at 27 GHz. (h) Radiation patterns at 29 GHz.

180° and reflection beam direction of  $\theta_r = 0^\circ$  is fabricated using the 3D-printing technology. The accuracy and maximum printable volume of the 3D printer used are  $25 \times 25 \times 100$   $\mu\text{m}$  and  $145 \times 145 \times 185$  mm, respectively. Fig. 7 shows the prototype of fabricated TRA antenna. As shown in Fig. 7 (a)–(c), the proposed TRA antenna is assembled using the mortise and tenon joints. More specifically, the whole TRA antenna is divided into two parts for manufacture as shown in Fig. 7 (c). The lower part acts as the base of the antenna and can be used to mount the other part which consists of elements

with different  $H_R$  values. Besides, different  $TAH$  values can be achieved by 3D printing the lower part, so there is no need to quantify the  $H_T$  value. It is worthwhile to mention that the fabrication tolerance will increase with the increasing number of elements. But this issue could be alleviated by using multi-material 3D printers. Fig. 7 (d) shows the measurement setup of the proposed antenna in an anechoic chamber during test. The distributions of  $H_T$  and 3-bit  $H_R$  values that generate the desired beams are shown in Fig. 7 (e) and (f).

For the antenna transmission function, the measured and simulated gain show small discrepancies as shown in Fig. 8 (a). As shown, a maximum gain of 24.4 dBi is realized at 25 GHz. The simulated and measured radiation patterns are given in Fig. 8 (b)–(f), which demonstrate good consistency. The measured results show that stable pencil-shaped beams with cross-polarization level lower than -22.2 dB are achieved across the whole operating bandwidth.

Fig. 9 (a) shows the measured and simulated gain of reflection. As shown, a maximum gain of 22.9 dBi is achieved at 27.5 GHz. The discrepancies between simulated and measured reflection gain may result from the blockage of feed antenna, cables and antenna holder. It can be seen from Fig. 9 that the measured radiation patterns are also in good agreement with the simulated patterns. All the measured SLLs are lower than -10 dB, and all the measured cross-polarization level are lower than -23.7 dB.

To demonstrate the merits of the proposed TRA antenna, Table I lists the comparison between the proposed antenna and other reported designs. As shown, the proposed antenna can operate over a wider bandwidth, especially for the radiation pattern bandwidth. Moreover, the proposed TRA antenna can generate independent beams for TA and RA functions within a wider bandwidth. Besides, the available beam range for TA function is  $130^\circ$ – $230^\circ$  while the beam range for RA function is  $-50^\circ$ – $50^\circ$ , making the proposed TRA more flexible for wide-range signal coverage. In addition, the proposed antenna can be fabricated by low-cost 3D-printing technology, avoiding the usage of multilayer PCB.

#### IV. CONCLUSION

In this paper, a wideband 3D-printed TRA antenna is proposed, whose transmission and reflection functions are determined by the polarization of incident wave. The proposed TRA element can control the transmission and reflection phase shift independently within a wide bandwidth, thereby facilitating the independent beam control of the TA and RA functions. A  $12 \times 12$  TRA is designed, fabricated, and measured. The measured results indicate that the transmission function has a maximum gain of 24.4 dBi with a operating bandwidth of 46.8% (18–29 GHz) and the reflection function has a maximum gain of 22.9 dBi with a operating bandwidth of 52.2% (17–29 GHz). The merits of wide bandwidth, high antenna gain, independent beam control capability, and low fabrication cost make it promising for a variety of wireless applications.

TABLE I  
COMPARISON BETWEEN THE PROPOSED ANTENNA AND REPORTED DESIGNS

Ref.	Peak Gain (dBi) TA/RA	Peak Aperture Efficiency (%) TA/RA	Operational Bandwidth (%) TA/RA	Gain Bandwidth (%) TA/RA	Independent Beam Control (available beam range)	Fabrication Technology
[16]	25.5/25	15/14	15/14 (1-dB gain bandwidth)	15(9.3–10.8 GHz) /14(—) (1-dB)	No	Laser cutting
[17]	21.4/20	36.3/37.4	9.1/11.2 (1-dB gain bandwidth)	9.1(9.4–10.3 GHz) /11.2(9.3–10.4 GHz) (1-dB)	Yes (—)	3-layers PCB
[18]	21.4/24.4	7/14	6.7/9.3 (1-dB gain bandwidth)	6.7(29.4–31.4 GHz) /9.3(29.1–31.9 GHz) (1-dB)	Yes (—)	3-layers PCB
[19]	24.8/24.3	45.6/48.2	45.2 (3-dB gain bandwidth) /18.6 (1-dB gain bandwidth)	22.6(10.1–12.7 GHz) /18.6(9.3–11.2 GHz) (1-dB)	Yes (—)	4-layers PCB
[20]	27.3/26.2	35.1/48.7	10.4/14.2 (1-dB gain bandwidth)	10.4(12.8–14.2 GHz) /14.2(9.8–11.3 GHz) (1-dB)	Yes (—)	4-layers PCB
<b>This work</b>	<b>24.4/22.9</b>	<b>38.5/28.1</b>	<b>46.8/52.2 (Stable radiation pattern bandwidth)</b>	<b>32.2(21.4–29.6 GHz) /27.2(21.6–28.4 GHz) (3-dB)</b>	<b>Yes(TA:130°–230° /RA: -50°–50°)</b>	<b>3D-Printing</b>

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